



Figure similar

### MLFB-Ordering data

6SL3210-1KE26-0AF1

Client order no. :

Order no. :

Offer no. :

Remarks :

Item no. :

Consignment no. :

Project :

Rated data		General tech. specifications	
<b>Input</b>		<b>Power factor <math>\lambda</math></b>	0.90 ... 0.95
<b>Number of phases</b>	3 AC	<b>Offset factor <math>\cos \varphi</math></b>	0.99
<b>Line voltage</b>	380 ... 480 V +10 % -20 %	<b>Efficiency <math>\eta</math></b>	0.98
<b>Line frequency</b>	47 ... 63 Hz	<b>Sound pressure level (1m)</b>	72 dB
<b>Rated current (LO)</b>	53.00 A	<b>Power loss</b>	0.77 kW
<b>Rated current (HO)</b>	44.00 A	<b>Ambient conditions</b>	
<b>Output</b>		<b>Cooling</b>	Air cooling using an integrated fan
<b>Number of phases</b>	3 AC	<b>Cooling air requirement</b>	0.055 m³/s
<b>Rated voltage</b>	400 V	<b>Installation altitude</b>	1000 m
<b>Rated power (LO)</b>	30.00 kW	<b>Ambient temperature</b>	
<b>Rated power (HO)</b>	22.00 kW	<b>Operation</b>	-20 ... 40 °C (-4 ... 104 °F)
<b>Rated current (IN)</b>	58.00 A	<b>Transport</b>	-40 ... 70 °C (-40 ... 158 °F)
<b>Rated current (LO)</b>	58.00 A	<b>Storage</b>	-40 ... 70 °C (-40 ... 158 °F)
<b>Rated current (HO)</b>	43.00 A	<b>Relative humidity</b>	
<b>Max. output current</b>	87.00 A	<b>Max. operation</b>	95 % RH, condensation not permitted
<b>Pulse frequency</b>	4.000 kHz	<b>Closed-loop control techniques</b>	
<b>Output frequency for vector control</b>	0 ... 240 Hz	<b>V/f linear / square-law / parameterizable</b>	Yes
<b>Output frequency for V/f control</b>	0 ... 550 Hz	<b>V/f with flux current control (FCC)</b>	Yes
<b>Overload capability</b>		<b>V/f ECO linear / square-law</b>	Yes
<b>Low Overload (LO)</b>	150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time	<b>Sensorless vector control</b>	Yes
<b>High Overload (HO)</b>	200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time	<b>Vector control, with sensor</b>	No
		<b>Encoderless torque control</b>	No
		<b>Torque control, with encoder</b>	No
		<b>Communication</b>	
		<b>Communication</b>	PROFINET

# SIEMENS

## Data sheet for SINAMICS G120C



Figure similar

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Mechanical data	
Degree of protection	IP20 / UL open type
Size	FSD
Net weight	18.80 kg
Width	200.0 mm
Height	472.0 mm
Depth	237.0 mm
Inputs / outputs	

### Standard digital inputs

Number	6
Switching level: 0→1	11 V
Switching level: 1→0	5 V
Max. inrush current	15 mA

### Fail-safe digital inputs

Number	1
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### Digital outputs

Number as relay changeover contact	1
Output (resistive load)	DC 30 V, 0.5 A
Number as transistor	1
Output (resistive load)	DC 30 V, 0.5 A

### Analog / digital inputs

Number	1 (Differential input)
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### Analog outputs

Number	1 (Non-isolated output)
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### PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy ±5 °C
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Standards	
Compliance with standards	UL, cUL, CE, C-Tick (RCM)
CE marking	EMC Directive 2004/108/EC, Low-Voltage Directive 2006/95/EC

Connections	
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### Signal cable

Conductor cross-section	0.15 ... 1.50 mm² (24 ... 16 AWG)
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### Line side

Version	screw-type terminal
Conductor cross-section	10.00 ... 35.00 mm² (8 ... 2 AWG)

### Motor end

Version	Screw-type terminals
Conductor cross-section	10.00 ... 35.00 mm² (8 ... 2 AWG)

### DC link (for braking resistor)

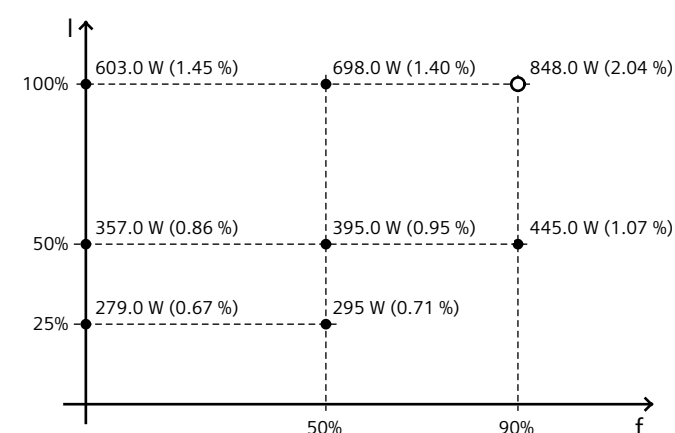
Version	Screw-type terminals
Conductor cross-section	10.00 ... 35.00 mm² (8 ... 2 AWG)
PE connection	Screw-type terminals

### Max. motor cable length

Shielded	200 m
Unshielded	300 m

Converter losses to EN 50598-2*	
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Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	-58.11 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

\*converted values