

MLFB-Ordering data

6SL3210-1KE31-7AF1



Client order no. : Order no. : Offer no. :

Item no.: Consignment no. : Project :

Remarks :			

Rated da	nta	General tech. specifications		
nput		Power factor λ	0.9	90 0.95
Number of phases	3 AC	Offset factor cos φ	0.9	99
Line voltage	380 480 V +10 % -20 %	Efficiency η	0.9	99
Line frequency	47 63 Hz	Sound pressure level (1m)	68	dB
Rated current (LO)	156.00 A	Power loss	1.5	57 kW
Rated current (HO)	144.00 A	Ambier	nt conditio	ns
Output				
Number of phases	3 AC	Cooling	Air coolin	g using an integrated fan
Rated voltage	400 V	Cooling air requirement	0.153 m³	ls
Rated power (LO)	90.00 kW	Installation altitude	1000 m	
Rated power (HO)	75.00 kW	Ambient temperature		
Rated current (IN)	164.00 A	Operation	-20 40	°C (-4 104 °F)
Rated current (LO)	164.00 A	Transport		°C (-40 158 °F)
Rated current (HO)	136.00 A	Storage	-40 70	°C (-40 158 °F)
Max. output current	272.00 A	Relative humidity		
Pulse frequency	4.000 kHz			
Output frequency for vector control	0 240 Hz	Max. operation	95 % RH,	condensation not permitted
Output frequency for V/f control	0 550 Hz	Closed-loop control techniques		hniques
		V/f linear / square-law / parame	eterizable	Yes
		V/f with flux current control (FG	CC)	Yes
Overload capability		V/f ECO linear / square-law		Yes
Low Overload (LO)		Sensorless vector control		Yes
150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a		Vester central with sensor		No

300 s cycle time

High Overload (HO)

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

Closed-loo	p contro	l techniques

Closed loop control t	cerninques
V/f linear / square-law / parameterizable	Yes
V/f with flux current control (FCC)	Yes
V/f ECO linear / square-law	Yes
Sensorless vector control	Yes
Vector control, with sensor	No
Encoderless torque control	No
Torque control, with encoder	No
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Communication **PROFINET**



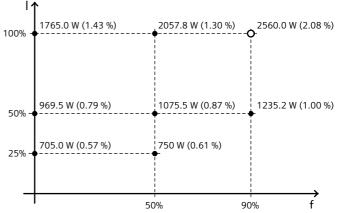
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Mechanical	data	Cor	Connections			
Degree of protection	IP20 / UL open type	Signal cable				
Size	FSF	Conductor cross-section	0.15 1.50 mm² (24 16 AWG)			
Net weight	63.50 kg	Line side				
Width	305.0 mm	Version	screw-type terminal			
Height	708.0 mm	Conductor cross-section	35.00 120.00 mm² (23 AWG)			
Depth	357.0 mm	Motor end				
Inputs / out	tputs	Version	Screw-type terminals			
Standard digital inputs		Conductor cross-section	35.00 120.00 mm² (23 AWG)			
Number	6	DC link (for braking resistor)				
Switching level: 0→1	11 V	Version	Screw-type terminals			
Switching level: 1→0	5 V	Conductor cross-section	35.00 120.00 mm² (23 AWG)			
Max. inrush current	15 mA	PE connection	Screw-type terminals			
Fail-safe digital inputs		Max. motor cable length				
Number	1	Shielded	300 m			
Digital outputs		Unshielded	450 m			
Number as relay changeover contact	1	Converter los	ses to EN 50598-2*			
Output (resistive load)	DC 30 V, 0.5 A	Efficiency class				
Number as transistor	1	Comparison with the reference co	IE2			
Output (resistive load)	DC 30 V, 0.5 A	100%)	-0.51 %			
Analog / digital inputs						
Number	1 (Differential input)	1765.0 W (1.43 %)	2057.8 W (1.30 %) 2560.0 W (2.08 %)			



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

Analog outputs

PTC/ KTY interface

Number

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy ±5 °C

1 (Non-isolated output)

Standards

Compliance with standards UL, cUL, CE, C-Tick (RCM)

EMC Directive 2004/108/EC, Low-Voltage **CE** marking Directive 2006/95/EC

^{*}converted values

Technical data are subject to change! There may be discrepancies between calculated and rating plate values.